

# **CRPS-Based Targeted Sequential Design with Application in Chemical Space**

Lea Friedli

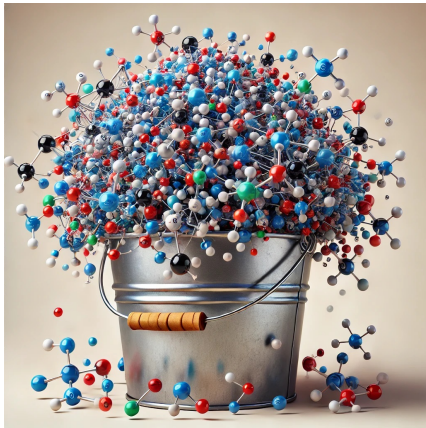
Engineering Risk Analysis Group  
Technical University of Munich

Joint work with A. Gautier, A. Broccard and D. Ginsbourger

mODa14

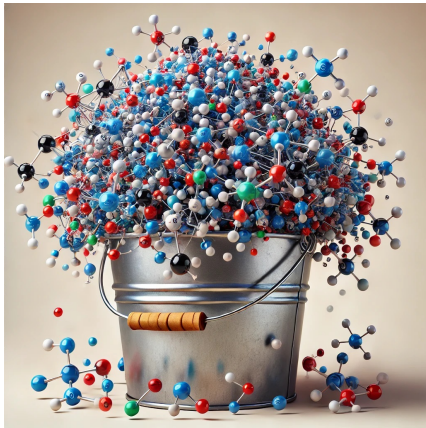
June 17, 2026

# Navigating molecular spaces



- Identify molecules with desired properties

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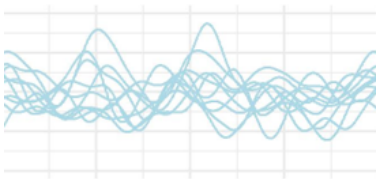
- ▶ Identify molecules with desired properties
- ▶ Predictive models to prioritize promising candidates

## GP modeling

Model function  $f : \mathcal{X} \rightarrow \mathbb{R}$  based on finite number of pointwise evaluations

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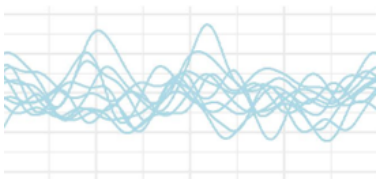
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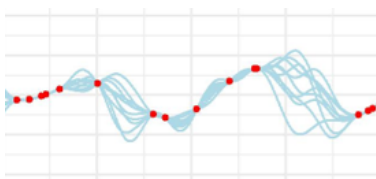
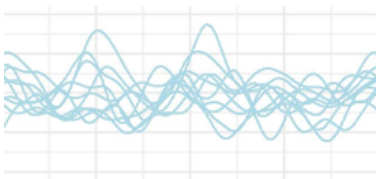
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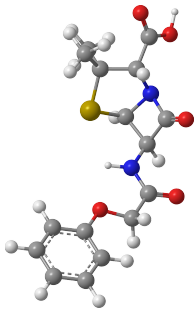
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- ▶  $\xi$  conditional on  $\mathcal{A}_n$  :  $\xi_n = (\xi_n(\mathbf{x}))_{\mathbf{x} \in \mathcal{X}} \sim \text{GP}(m_n, k_n)$

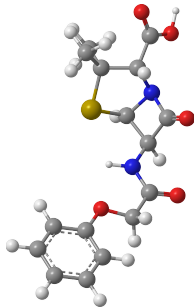
# Kernels for molecules



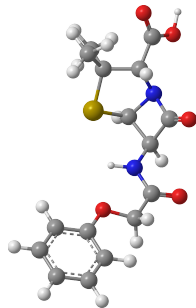
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## Fingerprints

Presence and absence of substructures  $\rightsquigarrow (1, 0, \dots, 1)$



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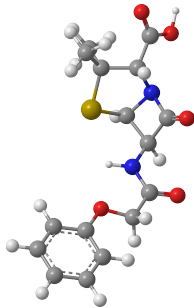
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## Tanimoto kernel [4]

Counts the number of common present features normalized by the total number of features present.

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## Fingerprints

Presence and absence of substructures  $\rightsquigarrow (1, 0, \dots, 1)$

## Tanimoto kernel [4]

Counts the number of common present features normalized by the total number of features present.

For  $\mathbf{x}, \mathbf{x}' \in \{0, 1\}^d$ ,  $d \geq 1$ :

$$k(\mathbf{x}, \mathbf{x}') := \begin{cases} \sigma_k^2 & \text{if } \langle \mathbf{x}, \mathbf{x} \rangle = \langle \mathbf{x}', \mathbf{x}' \rangle = 0, \\ \sigma_k^2 \frac{\langle \mathbf{x}, \mathbf{x}' \rangle}{\|\mathbf{x}\|^2 + \|\mathbf{x}'\|^2 - \langle \mathbf{x}, \mathbf{x}' \rangle} & \text{else,} \end{cases}$$

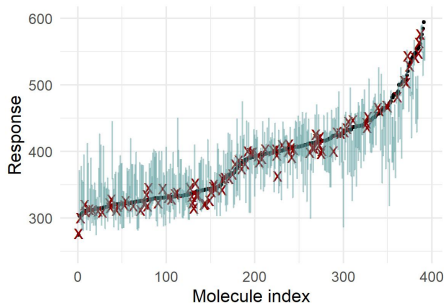
where  $\langle \mathbf{x}, \mathbf{x} \rangle = \mathbf{x}^\top \mathbf{x}$  and  $\sigma_k^2 > 0$ .

## Photoswitch dataset [6]

- ▶ Molecules undergoing reversible transformation when exposed to light
- ▶ Input: Morgan fingerprint, response: transition wavelength

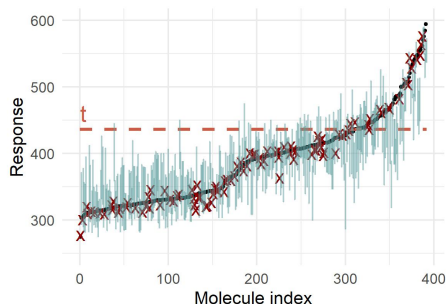
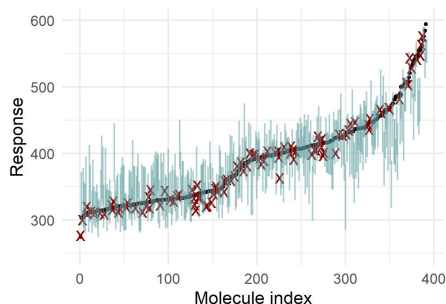
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- ▶ Excursion set of  $f$  above  $t \in \mathbb{R}$ :  $\Gamma := \{\mathbf{x} \in \mathcal{X} : f(\mathbf{x}) \geq t\}$

## Scoring Rules

- ▶ A scoring rule  $\mathcal{S} : \mathcal{F} \times \Omega \rightarrow \mathbb{R}$  represents the **loss** when the **predictive distribution**  $F \in \mathcal{F}$  is issued and the observation  $y \in \Omega$  materializes

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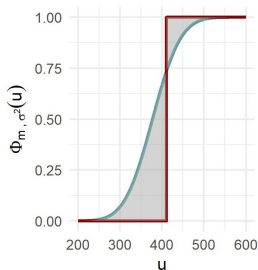
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- ▶ Scoring rules evaluate both **calibration** and **sharpness** of the prediction
- ▶ A scoring rule is **proper** relative to  $\mathcal{F}$  if no alternative forecast distribution  $F \in \mathcal{F}$  can yield a lower expected score than the true data-generating distribution  $Q \in \mathcal{F}$  [2]:

$$\mathbb{E}_{Y \sim Q} [\mathcal{S}(Q, Y)] \leq \mathbb{E}_{Y \sim Q} [\mathcal{S}(F, Y)]$$

# Continuous Ranked Probability Score

- **Continuous Ranked Probability Score** [CRPS; 5] for CDF  $F(\cdot)$  and  $y$ :

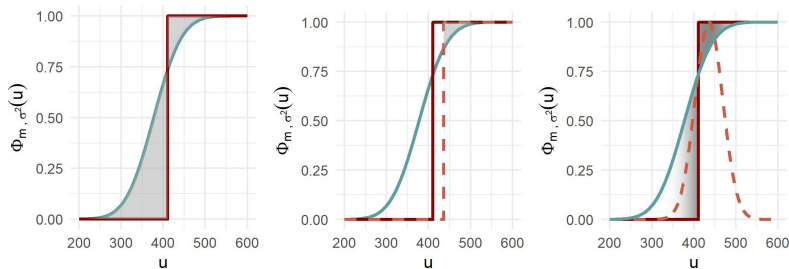
$$\text{CRPS}(F, y) = \int_{-\infty}^{\infty} [F(u) - \mathbb{1}\{y \leq u\}]^2 du.$$



## Threshold-weighted CRPS

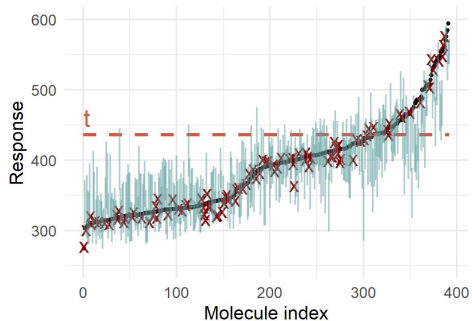
- ▶ Scoring rules [2]: Alignment predictive distribution and materialized value
- ▶ **Threshold-weighted CRPS** [5, 3] with weighting measure  $\nu$ :

$$\text{CRPS}_\nu(F, y) = \int_{-\infty}^{\infty} [F(u) - \mathbb{1}\{y \leq u\}]^2 d\nu(u).$$

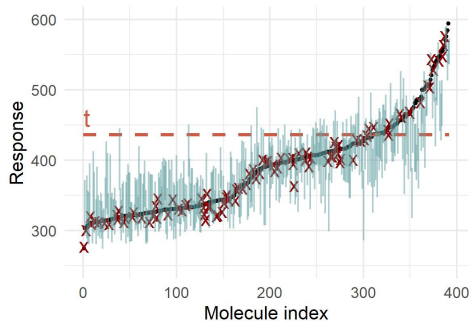


$$d\nu_1(u) = \mathbb{1}\{u \geq t\} d\lambda(u) \quad \text{and} \quad d\nu_2(u) = \frac{1}{\sigma_\nu} \phi\left(\frac{u-t}{\sigma_\nu}\right) d\lambda(u)$$

## From scoring to sequential design



## From scoring to sequential design



### One-step look-ahead (myopic) strategy:

- ▶ Current GP  $\xi_n \sim \text{GP}(m_n, k_n)$  with inputs  $\mathbf{x}_1, \dots, \mathbf{x}_n \in \mathcal{X}$
- ▶ Apply selection criterion to choose  $\mathbf{x}_{n+1}$
- ▶ Collect  $Z_{n+1}$  and update GP to  $\xi_{n+1} \sim \text{GP}(m_{n+1}, k_{n+1})$

## Targeted sequential design

- ▶ Select next  $\mathbf{x}_{n+i}$  such that it reduces the uncertainty of the future GP  $\xi_{n+i}$ , especially in (proximity to) the excursion set  $\Gamma$

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- ▶ During acquisition no materialized values  $\mathbf{y}$  for candidates
- ▶ Expected version of the threshold-weighted CRPS [also called entropy; 2]

$$\text{CRPS}_\nu(F) = \int_{-\infty}^{\infty} \text{CRPS}_\nu(F, \mathbf{y}') \, dF(\mathbf{y}') = \int F(u) (1 - F(u)) \, d\nu(u),$$

with weighting measure  $\nu(\cdot)$  and predictive CDF  $F(\cdot)$ .

## Expected threshold-weighted CRPS

For  $F = \Phi_{\mu, \sigma^2}$ ,  $d\nu_1(u) = \mathbb{1}\{t \leq u\}d\lambda(u)$  and  $\tilde{t} = (t - \mu)/\sigma$ , one obtains:

$$\text{CRPS}_{\nu_1}(\Phi_{\mu, \sigma^2}) = \sigma \left[ \tilde{t}\Phi(\tilde{t})^2 - \tilde{t}\Phi(\tilde{t}) + \frac{1}{\sqrt{\pi}} - \frac{1}{\sqrt{\pi}}\Phi(\tilde{t}\sqrt{2}) + 2\phi(\tilde{t})\Phi(\tilde{t}) - \phi(\tilde{t}) \right]$$

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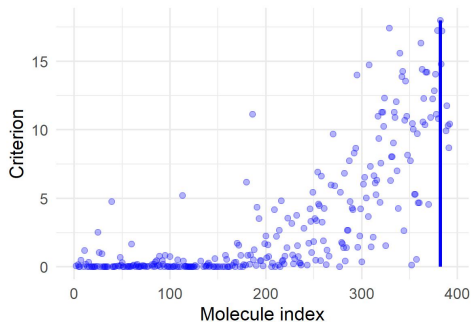
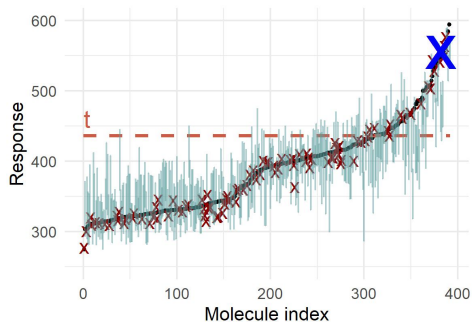
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For  $d\nu_2(u) = \frac{1}{\sigma_\nu}\phi\left(\frac{u-t}{\sigma_\nu}\right)d\lambda(u)$ , we get:

$$\text{CRPS}_{\nu_2}(\Phi_{\mu, \sigma^2}) = \Phi \left( \begin{pmatrix} 0 \\ 0 \end{pmatrix}; \begin{pmatrix} \mu - t \\ t - \mu \end{pmatrix}, \begin{pmatrix} \sigma_\nu^2 + \sigma^2 & -\sigma_\nu^2 \\ -\sigma_\nu^2 & \sigma_\nu^2 + \sigma^2 \end{pmatrix} \right)$$

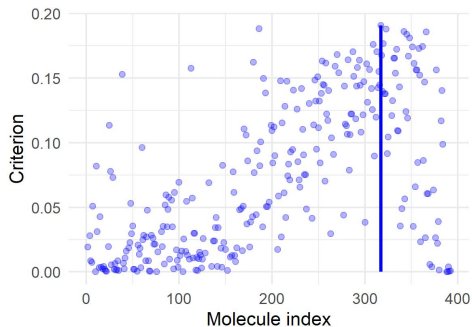
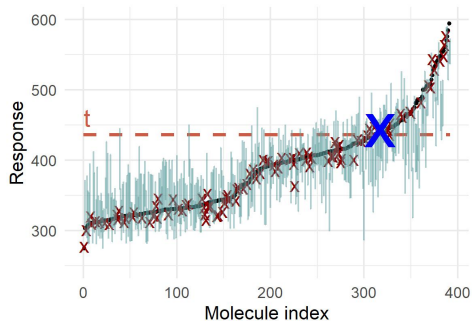
# Select the next molecule

Pointwise CRPS $_{\nu_1}$



# Select the next molecule

Pointwise CRPS $_{\nu_2}$



# Sports break: Decathlon

## Day 1

- ▶ 100 meters
- ▶ Discus throw
- ▶ Pole vault
- ▶ Javelin throw
- ▶ 400 meters

## Day 2

- ▶ 100/110 meters hurdles
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→ **Stepwise Uncertainty Reduction** [SUR; 1]

Uncertainty over entire domain

## SUR criteria

Given a GP model  $\xi_n$  at time  $n$ , select next acquisition point by minimizing

$$\mathbf{x} \mapsto J_n(\mathbf{x}) = \mathbb{E}_{n,\mathbf{x}}[\mathcal{H}(\xi_{n+1})]$$

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- ▶  $\mathcal{H}(\cdot)$ : uncertainty functional mapping the whole (updated) GP to real-value
- ▶  $\mathbb{E}_{n,\mathbf{x}}(\cdot)$  denotes the conditional expectation with respect to  $\xi_n$  when  $\mathbf{x}_{n+1} = \mathbf{x}$

## SUR criteria with $\text{CRPS}_\nu$

$$J_n(\mathbf{x}) = \mathbb{E}_{n,\mathbf{x}} \left[ \int \text{CRPS}_\nu(\xi_{n+1}(\mathbf{x}')) \mathbb{P}_{\mathcal{X}}(\mathrm{d}\mathbf{x}') \right] = \int \mathbb{E}_{n,\mathbf{x}} [\text{CRPS}_\nu(\xi_{n+1}(\mathbf{x}'))] \mathbb{P}_{\mathcal{X}}(\mathrm{d}\mathbf{x}')$$

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- Fix  $\mathbf{x}$  and  $\mathbf{x}'$ : marginal Gaussians  $\xi_{n+1}(\mathbf{x}') \sim \mathcal{N}(m_{n+1}(\mathbf{x}'), k_{n+1}(\mathbf{x}', \mathbf{x}'))$ ,

## SUR criteria with CRPS<sub>ν</sub>

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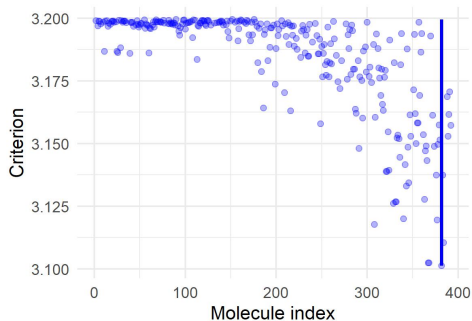
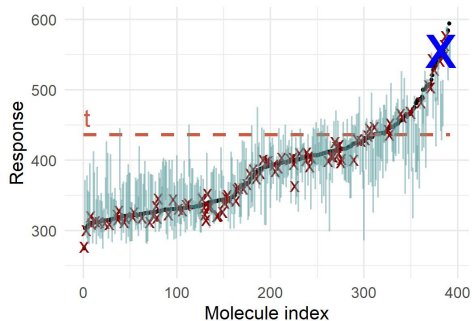
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- With  $\sigma_{n+1}^2 = k_{n+1}(\mathbf{x}', \mathbf{x}')$ ,  $\mu_n = m_n(\mathbf{x}')$ ,  $\alpha_n = \frac{k_n(\mathbf{x}, \mathbf{x}')}{\sqrt{k_n(\mathbf{x}, \mathbf{x}') + \tau^2}}$   
and  $N, \tilde{N}, V \stackrel{i.i.d.}{\sim} \mathcal{N}(0, 1)$ , we obtain:

$$\mathbb{E}_{n,\mathbf{x}} [\text{CRPS}_{\nu_1}(\xi_{n+1}(\mathbf{x}'))] = \sigma_{n+1} \mathbb{E} \left[ \left( N - \max \left( \tilde{N}, \frac{\mathbf{t} - \mu_n - \alpha_n V}{\sigma_{n+1}} \right) \right)_+ \right]$$

$$\mathbb{E}_{n,\mathbf{x}} [\text{CRPS}_{\nu_2}(\xi_{n+1}(\mathbf{x}'))] = \Phi \left( \begin{pmatrix} 0 \\ 0 \end{pmatrix}; \begin{pmatrix} \mu_n - \mathbf{t} \\ \mathbf{t} - \mu_n \end{pmatrix}, \begin{pmatrix} \sigma_{n+1}^2 + \alpha_n^2 + \sigma_\nu^2 & -\alpha_n^2 - \sigma_\nu^2 \\ -\alpha_n^2 - \sigma_\nu^2 & \sigma_{n+1}^2 + \alpha_n^2 + \sigma_\nu^2 \end{pmatrix} \right)$$

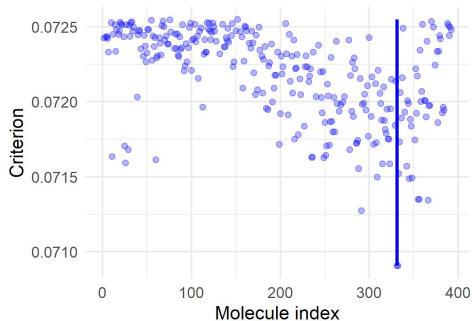
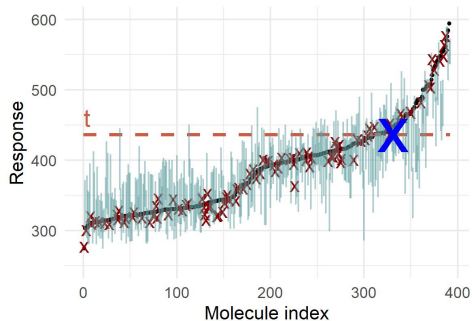
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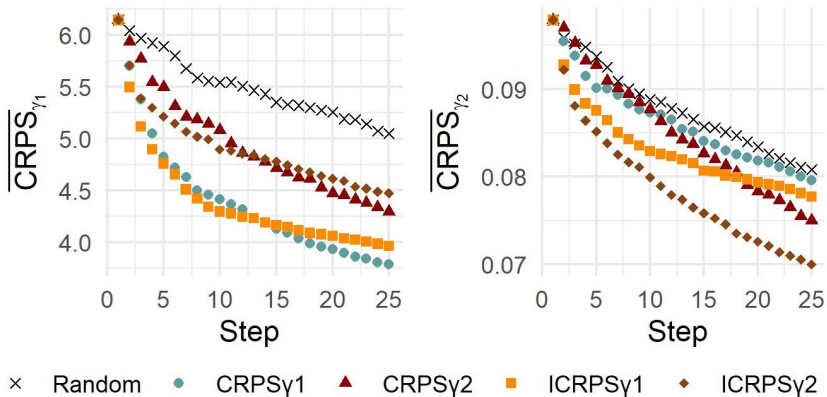
SUR CRPS <sub>$\nu_2$</sub>



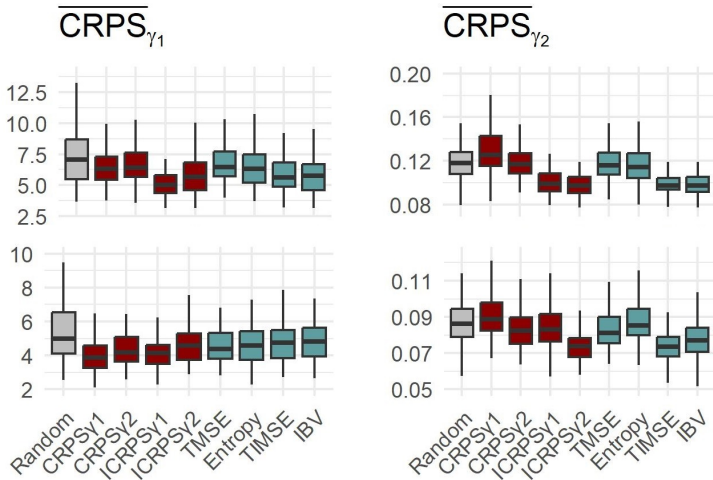
## Results Photoswitch

- ▶ 100 validation molecules (predictive mean as pink points)
- ▶ 30 initial molecules (red crosses), 50 added (blue crosses), 262 candidate molecules (predictive mean  $\pm 1$  SD as turquoise bars)
- ▶ Pointwise CRPS $_{\nu_1}$ :

## Results ( $n = 30$ and $\tilde{n} = 25$ )



## Comparison ( $n = 5$ and $\tilde{n} = 10, 35$ )



## Conclusions and outlook

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Preprint and code (including benchmarks on continuous functions):

- ▶ CRPS-Based Targeted Sequential Design with Application in Chemical Space  
(L.Friedli, A. Gautier, A. Broccard and D. Ginsbourger)
- ▶ GitHub/LeaFrie/GP\_sequentialCRPS

## References I

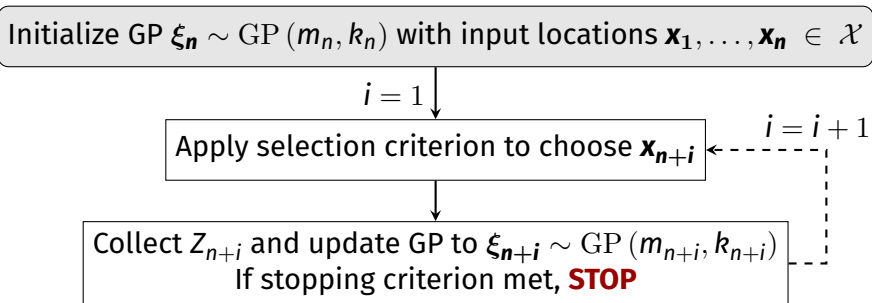
- [1] Julien Bect, Francois Bachoc, and David Ginsbourger. A supermartingale approach to Gaussian process based sequential design of experiments. Bernoulli, 25(4A):2883–2919, 2016.
- [2] Tilmann Gneiting and Adrian E Raftery. Strictly proper scoring rules, prediction, and estimation. Journal of the American Statistical Association, 102(477):359–378, 2007.
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## References II

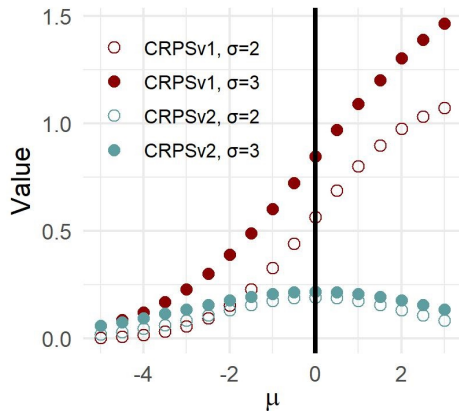
- [5] James E Matheson and Robert L Winkler. Scoring rules for continuous probability distributions. Management Science, 22(10):1087–1096, 1976.
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## Targeted sequential design

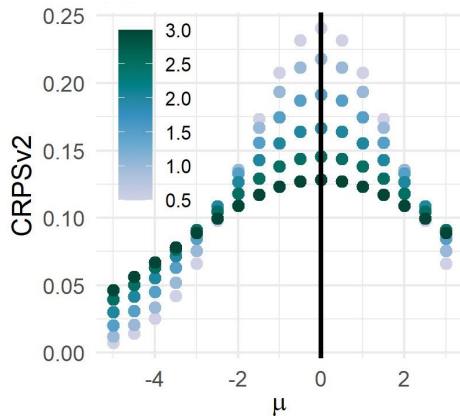
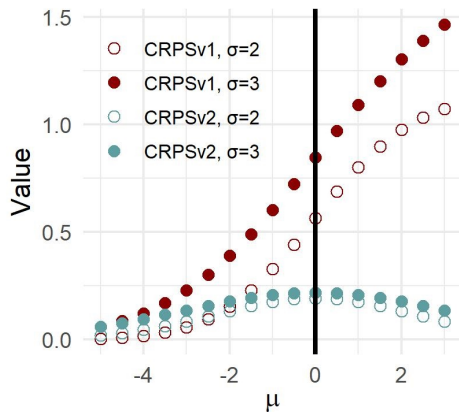
- ▶ Targeted scoring of GP predictions **for Sequential Design of Experiments**
- ▶ One-step look-ahead (myopic) strategy



Expected  $\text{CRPS}_{\nu_1}$  and  $\text{CRPS}_{\nu_2}$  for  $\Phi_{\mu, \sigma^2}$  and  $t = 0$



## Expected CRPS <sub>$\nu_1$</sub> and CRPS <sub>$\nu_2$</sub> for $\Phi_{\mu, \sigma^2}$ and $t = 0$



## Results Photoswitch

Pointwise CRPS $_{\nu_2}$ :